

**Amendments to the Claims:**

The following listing of claims will replace all prior versions, and listings, of claims in the application:

1. (Currently Amended) A ~~remote control~~ remote control for a heavy construction machine ~~of the type~~ comprising:
  - a ~~body~~ body which comprises at least one ~~cavity~~ (5, 63) cavity running between an ~~open end~~ open end ~~(6, 65)~~ opening onto at least a top ~~face~~ face ~~(7)~~ of the ~~body~~ body and a ~~bottom~~ bottom ~~(8, 66)~~ bottom at the opposite end to the open end,
  - at least one ~~first pushrod~~ first pushrod which runs between a ~~head end~~ head end ~~(12, 67)~~ and a ~~foot end~~ foot end ~~(13, 69)~~, which is mounted to slide back and forth in said at least one ~~cavity~~ cavity ~~(5, 63)~~ of the ~~body~~ body ~~(2)~~ in an axial direction between a rest position and a depressed position, and which is intended to control at least a first receiver external to the remote control, and
  - a ~~handle~~ handle ~~(4)~~ which comprises a ~~transverse skirt~~ transverse skirt ~~(10)~~ and which is mounted to pivot with respect to the ~~body~~ body ~~(2)~~ opposite the ~~top face~~ top face ~~(7)~~ of said ~~body~~ body ~~(2)~~ to control the back and forth movement of said ~~first pushrod~~ first pushrod ~~(3, 62)~~, the ~~skirt~~ skirt ~~(10)~~ simply resting against the ~~head end~~ head end ~~(12, 67)~~ of said ~~pushrod~~ pushrod ~~(3, 62)~~, and the axis (Y-Y) of the ~~handle~~ handle ~~(4)~~ making a variable acute angle with the axis (X-X) of the ~~pushrod~~ pushrod ~~(3, 62)~~, wherein the handle extends parallel to the axis of the pushrod when the pushrod is in the rest position,   
characterized in that ~~wherein~~ at least the ~~head end~~ head end ~~(12, 67)~~ of the ~~first pushrod~~ first pushrod ~~(3, 62)~~ can also move toward a protruding position which is on the opposite side of said rest position to the depressed position,
  - \_\_\_\_\_ in that first elastic return ~~means~~ means ~~(15, 74)~~ urge the ~~head end~~ head end ~~(12, 67)~~ of the ~~pushrod~~ pushrod ~~(3, 62)~~ toward its protruding position so that at least the ~~head~~

~~endhead end (12, 67)~~ of the first ~~pushrod~~pushrod (3, 62) has an autonomous upward movement,

~~the head (12, 67) of the first push rod (3, 62) has an autonomous rising movement to follow the skirt (10) when the handle (4) is swiveled, and~~

~~in that the remote controlcontrol (1) further comprises detection meansmeans (17) for detecting ~~the~~every position occupied by the head end of the first ~~pushrod~~pushrod (3, 62) comprising a rest position, a depressed position, and a protruding position occupied by the head end of the first pushrod between its protruding withdrawn and depressed pushed-down positions.~~

2. (Currently Amended) The remote controlcontrol (1) as claimed in claim 1, characterized in that ~~wherein~~ the detection meansmeans (17) are of the type free of mechanical contact.

3. (Currently Amended) The remote controlcontrol (1) as claimed in claim 2, characterized in that ~~wherein~~ the detection meansmeans (17) comprise a magnetmagnet which moves as one with the head end of the ~~pushrod~~pushrod (3, 62).

4. (Currently Amended) The remote controlcontrol (1) as claimed in claim 1, characterized in that ~~wherein~~ the cavitycavity (5) is stepped and comprises a first shouldershoulder (20) substantially transverse to the movement of the first ~~pushrod~~pushrod, and in that said ~~pushrod~~pushrod comprises an intermediate portionportion (22) which moves as one with the head endend (12) and the foot endend (13) of the ~~pushrod~~pushrod and is located between its head endend (12) and its foot endend (13) and delimits a top stopstop (23) and a bottom stopstop (24), the top stopstop (23) coming to rest against the first shouldershoulder (20) when the ~~pushrod~~pushrod is in the protruding position and the bottom stopstop (24) coming to rest against the bottombottom (8) of the cavitycavity (5) when said ~~pushrod~~pushrod is in the depressed position.

5. (Currently Amended) The remote ~~control~~<sup>(1)</sup>control as claimed in claim 4, characterized in thatwherein the first return means (15)means are housed in the cavity (5)cavity.

6. (Currently Amended) The remote ~~control~~<sup>(1)</sup>control as claimed in claim 4, characterized in thatwherein the first return means (15)means comprise a collar (26)collar borne by the intermediate portion (22)portion near the top stop (23) and a first compression spring (27) inserted between the collar (26) and the bottom (8) of the cavity (5).

7. (Currently Amended) The remote ~~control~~<sup>(1)</sup>control as claimed in claim 1, characterized in thatwherein the cavity (63)cavity comprises a shoulder (64)shoulder substantially transverse to the movement of the first pushrod (62)pushrod, and in that said pushrod (62)pushrod comprises a head end (67)end and a foot end (69)end that move together as one and are able to move translationally along the axis (X-X) of the pushrod (62)pushrod with respect to an intermediate portion (70)portion which is situated between the head end (67)end and the foot end (69)end and delimits a top stop (75)stop and a bottom stop (76)stop, the top stop (75)stop coming to rest against the shoulder (64)shoulder when the head end (67)end of the pushrod (62)pushrod is between its rest position and its protruding position and the bottom stop (76)stop coming to rest against the bottom (66) of the cavity (63)cavity when said pushrod (62)pushrod is in the depressed position.

8. (Currently Amended) The remote ~~control~~<sup>(1)</sup>control as claimed in claim 7, characterized in thatwherein the first elastic return means (74)means are housed between the head end (67)end of the pushrod and the intermediate portion (70) of the pushrod (62)pushrod.

9. (Currently Amended) The remote ~~control~~<sup>(1)</sup>control as claimed in claim 7, characterized in thatwherein the first elastic return means comprise a first compression spring

~~(74) spring inserted between the head end (67)end of the pushrod and the intermediate portion (70)portion of the pushrod (62)pushrod.~~

10. (Currently Amended) The remote ~~control~~ (1)control as claimed in claim 1, ~~characterized in that~~ ~~wherein~~ second elastic return ~~means~~ (30, 77)means are housed in the ~~cavity~~ (5, 63)cavity to return the first ~~pushrod~~ (3, 62)pushrod from its depressed position to its rest position.

11. (Currently Amended) The remote ~~control~~ (1)control as claimed in claim 10, ~~characterized in that~~ ~~wherein~~ the second return ~~means~~ (30) comprise a ~~ring~~ (31)ring concentric with the first ~~pushrod~~ (3)pushrod, a second compression ~~springspring~~ (32) inserted between the ~~ring~~ (31)ring and the ~~bottom~~bottom (8) of the ~~cavity~~ (3)cavity, and a peripheral ~~relief~~ (33) moving as one with the first ~~pushrod~~ (3) and intended to come to rest against the ~~ring~~ (31)ring, the ~~cavity~~ (5) further comprising a second ~~shoulder~~ (35) against which the ~~ring~~ (31)ring abuts when the first ~~pushrod~~ (3)pushrod is in the rest position.

12. (Currently Amended) The remote ~~control~~ (1)control as claimed in claim 10, ~~characterized in that~~ ~~wherein~~ the second return ~~means~~ (77) comprise a ~~collar~~ (78)collar borne by the intermediate ~~portion~~ (70)portion near the top ~~stop~~ (75)stop and a second compression ~~springspring~~ (79) inserted between the ~~collar~~ (78)collar and the ~~bottom~~bottom (66) of the ~~cavity~~ (62).

13. (Currently Amended) The remote ~~control~~ (1)control as claimed in claim 1, ~~characterized in that~~ ~~wherein~~ a second ~~pushrod~~ (50, 80, 87)pushrod is mounted in a second ~~cavity~~ (51, 82) of the ~~body~~ (2)body, the second ~~pushrod~~ (50, 80, 87)pushrod being elastically urged by a third compression ~~spring~~ (60, 86)spring in such a way that the force that has to be exerted on the ~~handle~~ (4)handle in order to depress one of the first (3, 62)first and second (50, 80, 87)second pushrods is more or less constant.

14. (Currently Amended) The remote ~~control~~<sup>(1)</sup>control as claimed in claim 13, characterized in thatwherein the second cavity (82)cavity is symmetric with the first cavity with respect to the axis of the ~~handle~~<sup>handle</sup> (4) in the rest position.

15. (Currently Amended) The remote ~~control~~<sup>(1)</sup>control as claimed in claim 13, characterized in thatwherein at least the head end (88)end of the second ~~pushrod~~<sup>(87)</sup>pushrod is able to move toward a protruding position which is on the opposite side of said rest position to the depressed position and in that elastic return ~~means~~<sup>(90)</sup>means urge the head end (88)end of the ~~pushrod~~<sup>(87)</sup>pushrod toward its protruding position so that at least the head end (88)end of the second ~~pushrod~~<sup>(87)</sup>pushrod has an autonomous upward movement.

16. (Currently Amended) The remote ~~control~~<sup>(1)</sup>control as claimed in claim 1, characterized in thatwherein the foot end (13, 69)end of the first ~~pushrod~~<sup>(3, 62)</sup>pushrod is mounted such that it passes through the ~~bottom~~<sup>(8, 66)</sup>bottom of the ~~cavity~~<sup>(5, 63)</sup>cavity and internally bears the ~~a~~<sup>the</sup> ~~magnet~~<sup>(40)</sup>magnet.

17. (Currently Amended) The remote ~~control~~<sup>(1)</sup>control as claimed in claim 16, characterized in thatwherein a Hall-effect ~~sensor~~<sup>(41)</sup>sensor is mounted in the ~~body~~<sup>(2)</sup>body of the remote ~~control~~<sup>(1)</sup>control facing the movement of the ~~magnet~~<sup>(40)</sup>magnet between the depressed and protruding positions of the first ~~pushrod~~<sup>(3, 62)</sup>pushrod.

18. (Currently Amended) The remote ~~control~~<sup>(1)</sup>control as claimed in claim 13, characterized in thatwherein the second ~~pushrod~~<sup>(50, 80, 87)</sup>pushrod is located on the opposite side of the axis of the ~~handle~~<sup>handle</sup> (4) to the first ~~pushrod~~<sup>(3, 62)</sup>pushrod.

19. (Currently Amended) The remote ~~control~~<sup>(1)</sup>control as claimed in claim 17, characterized in thatwherein the Hall-effect ~~sensor~~<sup>(41)</sup>sensor is potted in resin so that it is situated in a sealed location.